

VECTOR CALCULUS FORMULAS TO KNOW AND LOVE

(from Chapter 17 in Stewart)

First, in all of the following:

- The notation $\mathbf{r}(t) = \vec{r}(t)$ indicates a *position vector* that specifies a **curve** C . We assume that $a \leq t \leq b$. For example, $\mathbf{r} = 3 \cos(t) \mathbf{i} + 3 \sin(t) \mathbf{j} + 0 \mathbf{k}$, for $0 \leq t \leq 2\pi$.
- Then, $ds = |\mathbf{r}'(t)| dt$ = the arclength element along a curve, and $d\mathbf{r} = \mathbf{r}'(t) dt$ = the vector element along a curve.
- The notation $\mathbf{r}(u, v) = \vec{r}(u, v)$ indicates a *position vector* that is a function of *any two variables* and which specifies a **surface** S . We assume that the variables $(u, v) \in D$ for some domain D . For example, $\mathbf{r} = \langle r \cos(\theta), r \sin(\theta), 4 - r^2 \rangle$, for $0 \leq r \leq 1, 0 \leq \theta \leq 2\pi$.
- Then $dS = |\mathbf{r}_u \times \mathbf{r}_v| du dv$ = the surface area element on a surface, and $d\mathbf{S} = \mathbf{r}_u \times \mathbf{r}_v du dv$ = the oriented vector surface area element (with vector normal to the surface).
- The function $f(x, y, z)$ or $f(x, y, z)$ is a *scalar function* that returns a value: e.g., $f(x, y, z) = 3xy + \sin(z)$.
- The vector function $\mathbf{F}(x, y, z)$ or $\mathbf{F}(x, y, z)$ is a *vector field* that returns a vector: e.g., $\mathbf{F} = 2xy \mathbf{i} + x^2 \mathbf{j}$. We will also use the notation $\mathbf{F} = P \mathbf{i} + Q \mathbf{j}$ when referring to two-dimensional vector fields. For example, in the preceding vector field, $P = 2xy$ and $Q = x^2$.
- Because we write $\mathbf{F} = P \mathbf{i} + Q \mathbf{j}$ for two-dimensional \mathbf{F} , the following integral notations are equivalent: $\int \mathbf{F} \cdot d\mathbf{r} = \int P dx + Q dy$.

Make sure that the notations indicated above are obvious to you—to the point of your making the assumption that if you see $\mathbf{r}(t)$ written somewhere you immediately think “this defines a curve C ” and start thinking about what curve it is, etc.

Theorems of Vector Calculus

- **The Fundamental Theorem of Line Integrals**

$$\int_C \vec{\nabla} f \cdot d\mathbf{r} = f(\mathbf{r}(b)) - f(\mathbf{r}(a))$$

Note that this applies for *conservative* \mathbf{F} : $\int_C \mathbf{F} \cdot d\mathbf{r} = f(\mathbf{r}(b)) - f(\mathbf{r}(a))$.

- **Green’s Theorem**

$$\iint_D \left(\frac{\partial Q}{\partial x} - \frac{\partial P}{\partial y} \right) dA = \oint_C \mathbf{F} \cdot d\mathbf{r}$$

Here D is a region in the xy -plane, and C is the curve that bounds D , oriented counterclockwise. Therefore: Green’s theorem is **only applicable** to **closed** curves C that are in the xy -plane. Also note that for two-dimensional functions $\mathbf{F} \left(\frac{\partial Q}{\partial x} - \frac{\partial P}{\partial y} \right) = \text{curl } \mathbf{F} \cdot \mathbf{k}$ —and that \mathbf{k} is the normal vector for a region (surface) in the xy -plane.

- **Stokes’ Theorem**

$$\iint_S \text{curl } \mathbf{F} \cdot d\mathbf{S} = \oint_C \mathbf{F} \cdot d\mathbf{r}$$

Here \mathbf{S} is any bounded surface S , and C is the curve that bounds S , oriented “counterclockwise.” Therefore: Stokes’ theorem is only applicable to the (odd) **cases when we want to find** $\iint_S \text{curl } \mathbf{F} \cdot d\mathbf{S}$, and/or **cases when we want to find** $\oint_C \mathbf{F} \cdot d\mathbf{r}$ and there is a “nice” surface S bounded by C .

This semester we spent much (much) less time on this last theorem, so it is “less important” in some sense or another.

- **the Divergence Theorem (Gauss’ Theorem)**

$$\iiint_E \text{div } \mathbf{F} dV = \iint_S \mathbf{F} \cdot d\mathbf{S}$$

Here \mathbf{S} is the **surface that bounds the volume** E . Therefore: the divergence theorem is most applicable to **cases when we want to find the flux through a closed surface**.